# Deconstruct, Analyse, Reconstruct: How to Improve Tempo, Beat, and Downbeat Estimation

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## Act I: Beat Tracking with TCNs

Introduce temporal convolutional networks for beat tracking



# Act III: Deconstruct, Analyse, Reconstruct

Include downbeats as a new multitask learning target Update the convolution and max pooling layers Incorporate two dilation rates that are multiples of each other Incorporate data augmentation when training



## Downbeat multitask learning target

Joint estimation: beats and downbeats Sequential estimation: beats then downbeats

DBN downbeats beats

#### Updated conv. & max pooling



## **Updated TCN**

Introduce a "double dilation" rate to allow longer term temporal dependencies to be captured by the network

### Data augmentation

To increase the network's exposure to a wider range of tempi, we generate multiple versions of the log magnitude spectrogram at different hop sizes and adjust the beat, downbeat, and tempo targets accordingly



### **Ablation Study**

To demonstrate the benefit across each task of each introduced modification we present an ablation study



# Main Results: Unseen Datasets

#### **Tempo Estimation**

	Accuracy 1	Accuracy 2			
ACM Mirum					
Gkiokas et al. [50]	0.725	0.979			
Percival and Tzanetakis [44]	0.733	0.972			
Schreiber and Müller [17]	0.781	0.976			
Böck et al. [20]	0.749	0.974			
Foroughmand & Peeters [18]	0.733	0.965			
Ours	0.841	0.990			
GiantSteps					
Gkiokas et al. [50]	0.721	0.922			
Percival and Tzanetakis [44]	0.506	0.956			
Schreiber and Müller [17] *	0.821	0.971			
Böck et al. [20]	0.764	0.958			
Foroughmand & Peeters [18] *	0.836	0.979			
Ours	0.870	0.965			
GTZAN					
Gkiokas et al. [50]	0.651	0.931			
Percival and Tzanetakis [44]	0.658	0.924			
Schreiber and Müller [17]	0.769	0.926			
Böck et al. [20]	0.673	0.938			
Foroughmand & Peeters [18]	0.697	0.891			
Ours	0.830	0.950			

#### **Beat Tracking**

	F-measure	CMLt	AMLt
	GTZAN		
Böck et al. [5]	0.864	0.768	0.927
Davies and Böck [22]	0.843	0.715	0.914
<b>Ours (beat tracking)</b>	0.883	0.808	0.930
<b>Ours (joint tracking)</b>	0.885	0.813	0.931

#### **Downbeat Tracking**

Ours (joint tracking)	0.672	0.640	0.832
<b>Ours (sequential tracking)</b>	0.654	0.619	0.817
Durand et al. [8]	0.607	0.480	0.774
Böck et al. [28]	0.640	0.577	0.824
$GT_{z}$	ZAN		
	F-measure	CMLt	AMLt
-	GT Böck et al. [28] Durand et al. [8] <b>Ours (sequential tracking)</b> <b>Ours (joint tracking)</b>	F-measure   GTZAN   Böck et al. [28] 0.640   Durand et al. [8] 0.607   Ours (sequential tracking) 0.654   Ours (joint tracking) 0.672	F-measure CMLt   GTZAN 0.640 0.577   Durand et al. [8] 0.607 0.480   Ours (sequential tracking) 0.654 0.619   Ours (joint tracking) 0.672 0.640

# Main Findings

We establish a new state of the art in all three tasks, with the most prominent gains coming in totally unseen test datasets.

We observe a promising "closing of the gap" between stricter and weaker evaluation methods indicating our approach is better able to reproduce the metrical level chosen by the annotator.

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